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COUPLING FINITE ELEMENTS APPLIED TO HYDRAULIC ANALYSIS IN SATURATED POROUS MEDIA

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Abstract. *This paper presents a new methodology to couple non-matching Finite Element (FE) meshes used to model fluid flow in saturated porous media. The proposed technique is based on the definition of Coupling Finite Elements (CFEs), which are strategically employed to ensure the continuity of pressure between independent (non-matching) FE meshes. This technique is particularly powerful to handle cases where specific regions of the material need to be discretized with highly refined FE meshes. In addition, the non-matching meshes are coupled without increasing the total number of degrees of freedom of the problem. Two numerical examples (2D problem) with non-matching meshes are analyzed to validate the proposed method. The results obtained for the matching and non-matching meshes are similar, demonstrating the efficiency of the method.*

Keywords: *Darcy's law, non-matching meshes, coupling finite elements, porous media*

1. INTRODUCTION

Numerical modeling and simulation of fluid flow in porous media has received increasing attention mainly due to the computational development. The finite element method (FEM) is one of the techniques widely used to solve this kind of problem and its accuracy is directly associated with the mesh discretization. However, refined meshes require more computational effort when compared to coarse meshes. A possible solution to overcome that issue is to subdivide the domain into fully independent subdomains with different degrees of refinement and use coupling techniques to connect the non-matching meshes. This strategy has been applied in adaptive mesh refinement (Wu *et al.* (2009), Lo *et al.* (2010) and Lim *et al.* (2012)), multiphysical analysis (Dureisseix and Bavestrello (2006), Hüeber and Wohlmuth (2009) and Bazilevs *et al.* (2012)) and multiscale problems (Unger and Eckardt (2011), Lloberas-Valls *et al.* (2012) and Thirunavukkarasu and Guddati (2012)).

In multiphysical problems, de Boer *et al.* (2007) compare six distinct methods to deal with the transfer of information between non-matching meshes, which are based on: nearest neighbour interpolation (Thévenaz *et al.*, 2000); an orthogonally designed point of another mesh (Farhat *et al.* (1998), Cebral and Lohner (1997) and Loehner *et al.* (1998)); splines interpolation (Thévenaz *et al.*, 2000); radial basis functions (Smith *et al.*, 2000); Lagrange multipliers (Ransom, 2002) and optimal way, also named by Mortar method (Baaijens, 2001).

In the context of mechanical problems, Bitencourt Jr *et al.* (2015) proposed an approach to coupling non-matching meshes, based on the use of coupling finite elements (CFE). The applicability of the technique was illustrated for different 2D and 3D examples. The authors demonstrated that the CFEs can ensure continuity of the displacement field, without increasing the number of degrees of freedom of the problem. Rodrigues *et al.* (2018) used the same CFEs for the adaptive concurrent multiscale modeling of concrete.

The CFE technique was successfully used by Vafajou *et al.* (2018) to study the behavior of the fluid flow in a naturally fractured porous medium. The authors inserted the discontinuities in the mesh using the coupling elements and compared the performance of this technique against other numerical methods.

This paper presents the application of CFEs to couple non-matching meshes to model the behavior of fluid flow in

domains with different permeabilities. The numerical 2D hydraulic examples compare the pressure fields obtained from matching and non-matching meshes.

2. GOVERNING EQUATIONS FOR HYDRAULIC PROBLEMS

Considering an isotropic medium, the fluid flow given by Darcy's Law can be written by:

$$\mathbf{q} = -\frac{\kappa}{\mu}(\nabla p - \rho_f \mathbf{g}) \quad (1)$$

where, \mathbf{q} is the flux vector, κ represents the intrinsic permeability of the porous medium, μ is the fluid viscosity, ∇p is the gradient of pressure, ρ_f is the specific mass of the fluid and \mathbf{g} is the gravity acceleration.

The fluid mass conservation equation for the permanent regime can be written as:

$$\nabla \cdot \mathbf{q} = 0 \quad (2)$$

The boundary conditions of the hydraulic problem are given by $p = \bar{p}$ on Γ_p and $\mathbf{q} \cdot \mathbf{n} = \bar{q}$ on Γ_q , where \bar{p} and \bar{q} are the pressure and flow prescribed on the boundaries Γ_p e Γ_q , respectively.

3. COUPLING FINITE ELEMENTS (CFEs)

Figure 1 illustrates the technique proposed by Bitencourt Jr *et al.* (2015) where the domain (Ω) is subdivided into two other subdomains, Ω^1 and Ω^2 , discretized with non-matching meshes. As a consequence, the interface $\Gamma_{12} = \Gamma_1 \cap \Gamma_2$ of these subdomains is a non-matching interface containing loose nodes, represented in blue in Fig. 1.

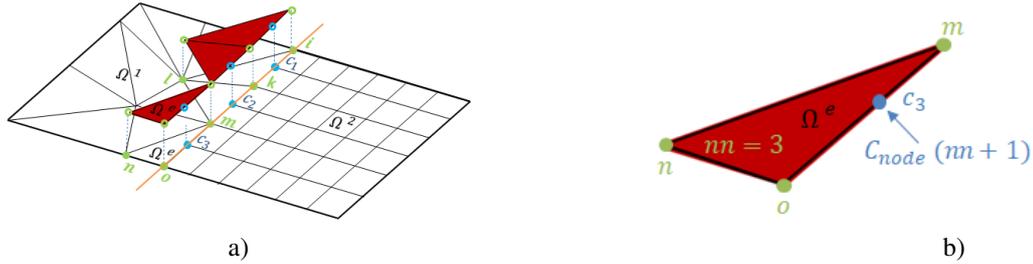


Figure 1: Coupling technique for non-matching FE meshes. a) Coupling procedure for 2D problem with two non-matching meshes. b) Triangular coupling FE. (adapted from Bitencourt Jr *et al.* (2015)).

This coupling between the meshes is based on the insertion of Coupling Finite Elements (CFEs), shown in red in Fig. 1a. The CFEs are derived from standard isoparametric finite element by adding one extra node, called coupling node (C_{node}). Since these elements share nodes of both meshes, no additional degrees of freedom are introduced to the problem. Another advantage is that the technique can be easily incorporated into a conventional FE code, since no special formulation or integration scheme are required.

3.1 CFEs Formulation

The pressure field at any material point \mathbf{X} inside a finite element can be approximated in terms of its nodal pressures by:

$$\mathbf{P}(\mathbf{X}) = \sum_i^{nn} N_i(\mathbf{X})p_i \quad (3)$$

where nn is the number of nodes of the element, $N_i(\mathbf{X})$ ($i = 1, nn$) are the standard shape functions and p_i are the nodal pressures.

In order to establish a connection between the non-matching meshes, the difference between the pressure at the coupling node, C_{node} , and its corresponding material point (\mathbf{X}_c) is calculated using the standard shape functions $N_i(\mathbf{X}_c)$, as follows:

$$\llbracket \mathbf{P} \rrbracket = \mathbf{P}_{nn+1} - \mathbf{P}(\mathbf{X}_c) = \mathbf{P}_{nn+1} - \sum_i^{nn} N_i(\mathbf{X}_c)p_i = \mathbf{B}_e \mathbf{P}_e \quad (4)$$

where $[\mathbf{P}]$ is the relative pressure and \mathbf{B}_e and \mathbf{P}_e are given by:

$$\mathbf{B}_e = [-\mathbf{N}_1(\mathbf{X}_c) \quad -\mathbf{N}_2(\mathbf{X}_c)\dots \quad -\mathbf{N}_{nn}(\mathbf{X}_c) \quad \mathbf{1}] \quad (5)$$

$$\mathbf{P}_e = [p_1 \quad p_2\dots \quad p_{nn} \quad p_{nn+1}]^T \quad (6)$$

Exploring the correspondence between mechanical and hydraulic problems (Segura and Carol (2004) and Vafajou *et al.* (2018)) the internal virtual work δW^{int} for the CFE is given by:

$$\delta W^{int} = \delta[\mathbf{P}]\mathbf{q}([\mathbf{P}]) \quad (7)$$

where $\mathbf{q}([\mathbf{P}])$ is the flux associated with the relative pressure $[\mathbf{P}]$ and $\delta[\mathbf{P}]$ is an arbitrary virtual relative pressure. Using the same approximation for the relative pressure and the virtual relative pressure given by Eq. 5, the internal flow vector \mathbf{q}_e^{int} and the corresponding permeability matrix \mathbf{K}_e can be obtained by:

$$\mathbf{q}_e^{int} = \mathbf{B}_e^T \mathbf{q}([\mathbf{P}]) \quad (8)$$

$$\mathbf{K}_e = \frac{\partial \mathbf{q}_e^{int}}{\partial \mathbf{P}_e} = \mathbf{B}_e^T \mathbf{C} \mathbf{B}_e \quad (9)$$

where, \mathbf{C} is a matrix of constants assuming high values that play the rule of penalty factors enforcing a null pressure drop ($[\mathbf{P}] = 0$), allowing the coupling of the non-matching meshes.

4. NUMERICAL EXAMPLES

The main purpose of the numerical examples is verify the ability of the CFEs to solve hydraulic problems. Therefore, to simplify the model, gravitational effects are disregarded and all the domains are completely saturated by only one fluid. The problems are divided in two cases: (i) insertion and (ii) application cases.

4.1 Insertion case

Subdomains with the same permeability

The first example considers a stationary fluid flow in a 1.2×1.2 m 2-dimensional fully saturated porous medium. The domain is composed of two subdomains, Ω^1 and Ω^2 , where Ω^2 is surrounded by Ω^1 (Fig. 2). In order to test the CFE method, different discretizations are adopted for Ω^1 , i.e. a refined (Mesh A) and a coarse (Mesh B) meshes (Fig. 2a,b, respectively), while Ω^2 remains with the same discretization. Thus, the total domain presents a matching mesh (Mesh A) and a non-matching mesh (Mesh B). Therefore, in the Mesh B (coarse), Ω^1 is coupled to the Ω^2 via CFEs (Fig. 2b).

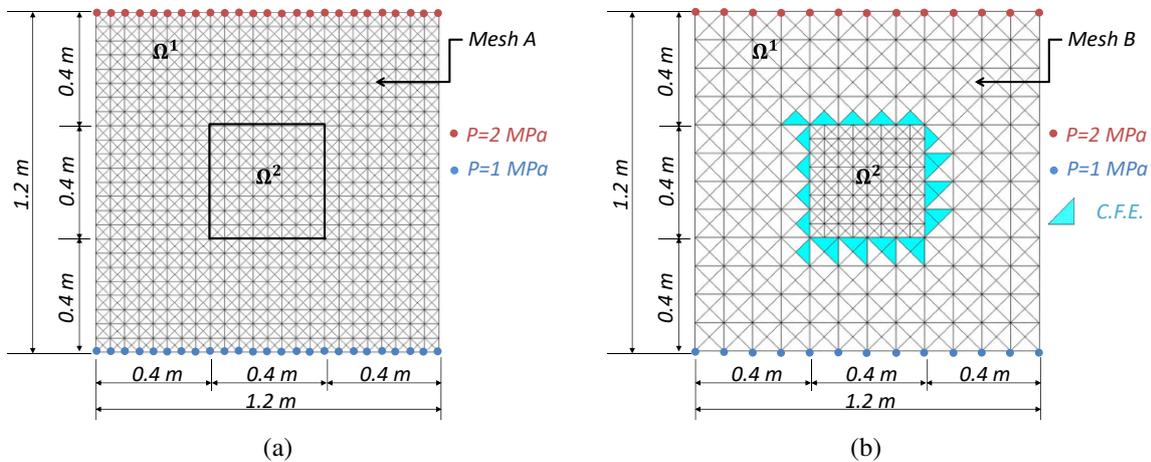


Figure 2: Sample with square geometry discretized by: a) matching triangular FEs. b) non-matching triangular FEs with two different scales of refinement.

The coupling between the meshes is verified imposing a pressure gradient ($\Delta p = 1.0$ MPa) in the whole domain. In this case, Ω^1 and Ω^2 have the same permeability, i.e. $k_{\Omega^1} = k_{\Omega^2} = 1.0 \times 10^{-15}$ m². Figures 3a and 3b shows the

pressure field in both meshes. Figure 3c compares the pressure along different heights ($y_1 = 0.3m, y_2 = 0.4m, y_3 = 0.6m, y_4 = 0.8m, y_5 = 0.9m$), where M represents the matching mesh, while NM represents the non-matching meshes. The good agreement between the responses obtained using matching and non-matching meshes shows that CFEs were able to couple the non-matching meshes.

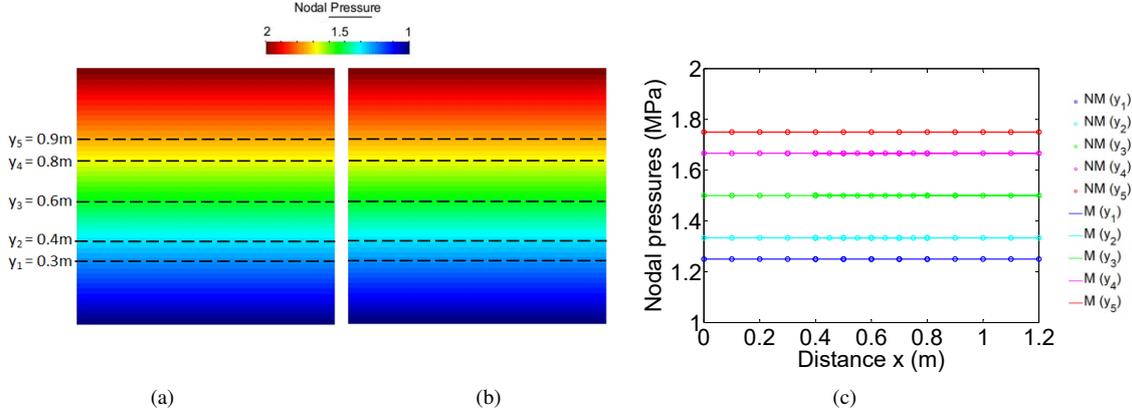


Figure 3: First example. Pressure field of the (a) matching and (b) non-matching meshes and (c) convergence analysis between the meshes.

Subdomains with different permeability

In the second case, the permeability of Ω^2 was replaced by $k_{\Omega^2} = 1.0 \times 10^{-14} m^2$. Figures 4a and 4b show the pressure field for both meshes. As expected, the higher permeability associated to Ω^2 disturbs the pressure field, since the more permeable region induces a preferential pathway to the fluid flow.

Figure 4c presents a comparison between the results from the distinct meshes along different heights ($y_1 = 0.3m, y_2 = 0.4m, y_3 = 0.6m, y_4 = 0.8m, y_5 = 0.9m$). In this case, a good agreement is also obtained, indicating an efficient coupling between non-matching meshes.

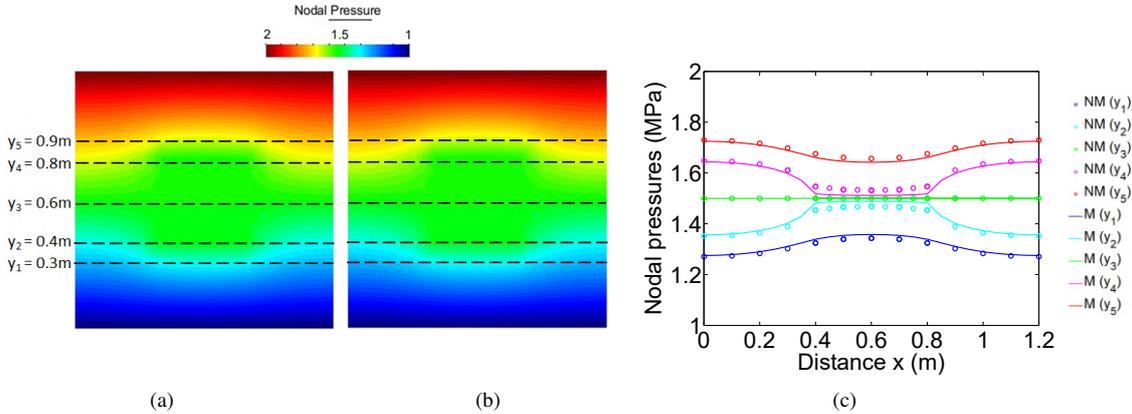


Figure 4: Second example. Pressure field of the (a) matching and (b) non-matching meshes and (c) convergence analysis between the meshes.

For this second example, the equivalent permeability of each mesh (i.e. matching and non-matching meshes) was calculated according to the total flow rate leaving from only one boundary with prescribed pressure. The following expression gives the equivalent permeability:

$$K_{eq} = - \sum_{i=1}^{nnp} Q_i \frac{\mu L}{A \Delta p} \quad (10)$$

where Q_i is the flow rate in the node i , nnp is the number of nodes in the boundary, Δp is the pressure difference, L is the distance between the boundaries with prescribed pressures and A is the area of the boundary (for a unitary thickness, $A = L$). Table 1 compares these permeabilities, where is possible verify similar results. Note that, considering that the matching mesh provides a more accurate result, the relative error (difference) is less than 0.4%.

Table 1: Values of the equivalent permeabilities K_{eq} .

Equivalent Permeability - K_{eq}	
	$K_{eq} (m^2)$
Matching Meshes	1.215250376E-15
Non-Matching Meshes	1.219482775E-15
Relative Error	0.352%

4.2 Application case: geologic fault

The second numerical case considers a fully saturated reservoir sectioned by a geologic fault and isolated by two other regions (Overburden and Underburden), where each adopted intrinsic permeability is presented in Table 2. Two wells (injection and production) are positioned within the reservoir on opposite sides to the fault as show in Fig. 5. The injection well operates at a constant pressure equal to $4MPa$, while the production well operates at a constant pressure equal to $-4MPa$ (Fig. 5).

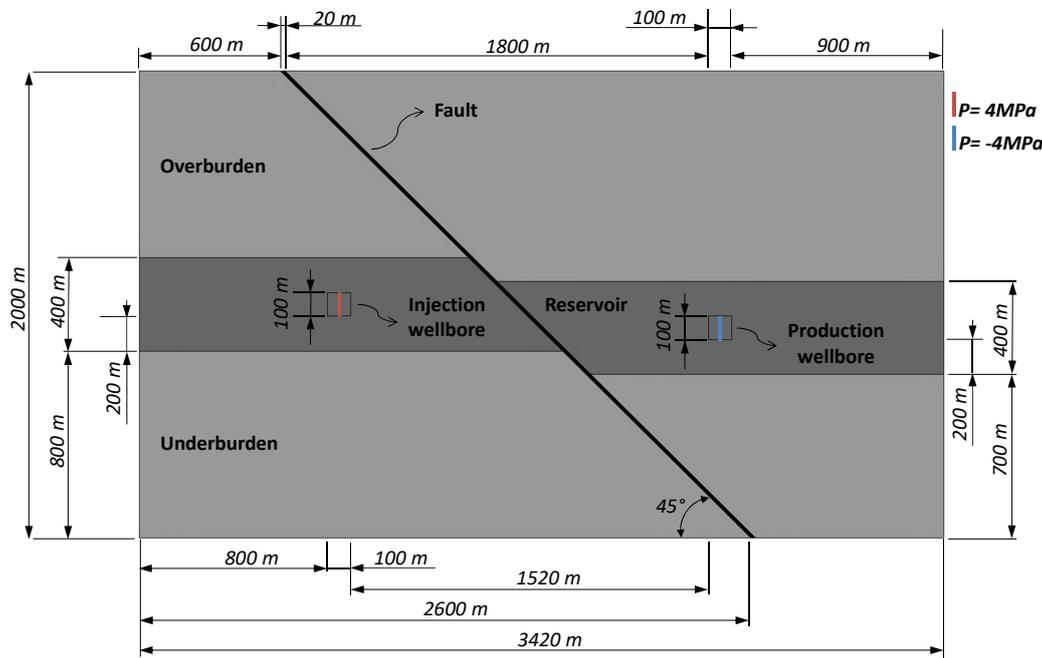


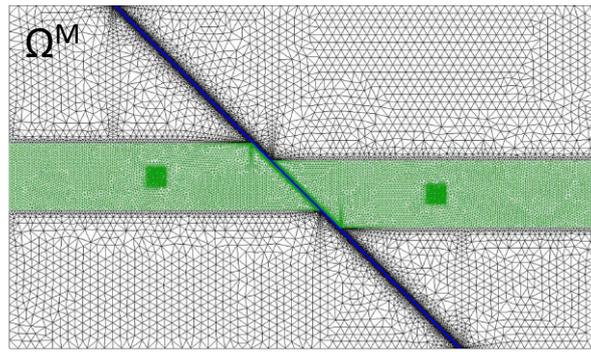
Figure 5: Schematic representation for the second case.

Table 2: Values of the permeabilities of materials (k).

	Reservoir	Fault	Overburden and Underburden
$k(m^2)$	1.0×10^{-12}	1.0×10^{-14}	1.0×10^{-22}

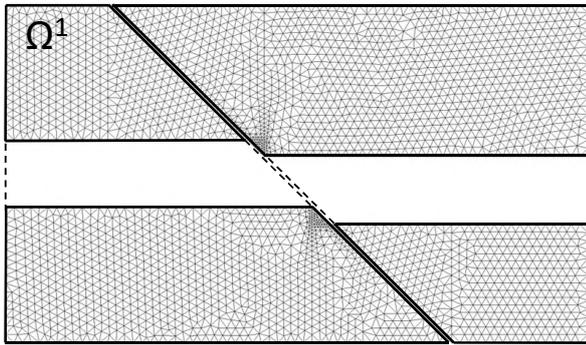
In order to verify the efficiency of the CFE technique, a comparison between matching and non-matching meshes in terms of pressure field was performed. Figure 6 illustrates the matching mesh configuration obtained for the entire domain, Ω^M domain. Figure 7 shows the steps for the construction of the non-matching mesh, since the domain Ω^{NM} corresponds to the union of the independent subdomains Ω^1 , Ω^2 , Ω^3 and Ω^4 . The number of elements used for construction of the matching mesh was 61,124, while for non-matching mesh was 46,402 elements. This reduction in the number of elements represents a decrease in the computational effort, once the degrees of freedom of the problem are also reduced by using a more optimized mesh.

Figures 8a and 8b show the pressure field for matching (M) and non-matching mesh (NM), respectively. A good similarity between the pressure fields can be observed. Figures 9a, 9b and 9c represent the values of nodal pressures along sections $S1$, $S2$ and $S3$, respectively. Section $S1$ is located at a height of $950m$ and is mostly contained within the reservoir, since, in its central part, the section crosses the fault. Sections $S2$ and $S3$ are located at a distance of $850m$ and $2470m$, respectively, and cross the four regions (Underburden, Reservoir, Overburden and Fault). It is noted that all three sections chosen have, at least, an interface region between the meshes, which allows evaluating the critical points of the technique of CFEs. Figures 9b and 9c for example, highlight part of the curve that represents the transition region

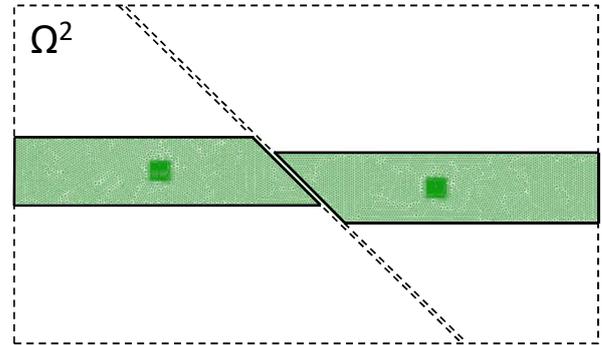


(a)

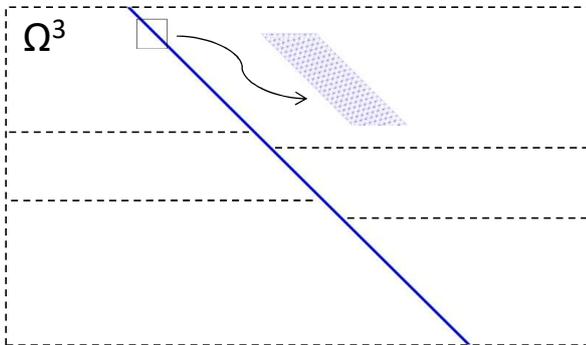
Figure 6: Geometry discretized by matching triangular FEs.



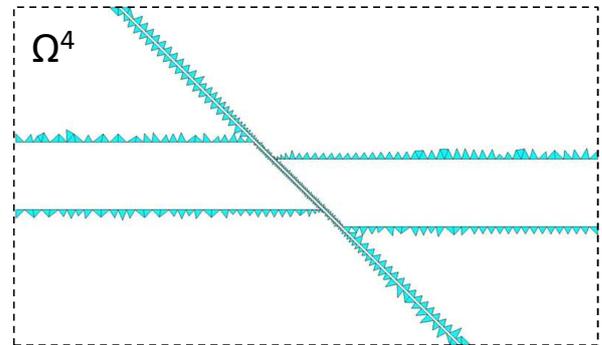
(a)



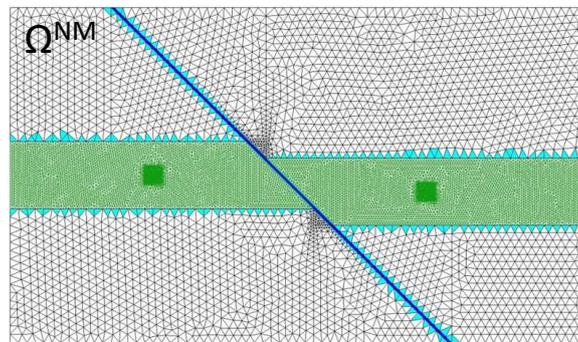
(b)



(c)



(d)



(e)

Figure 7: Non-matching mesh construction. (a) Underburden and Overburden meshes. (b) Reservoir mesh. (c) Fault mesh. (d) Creation of CFEs to couple all subdomains. (e) Geometry discretized by the CFEs technique.

between Underburden/Overburden and fault. Similarly the matching mesh, the non-matching mesh can also characterize the continuity between the regions.

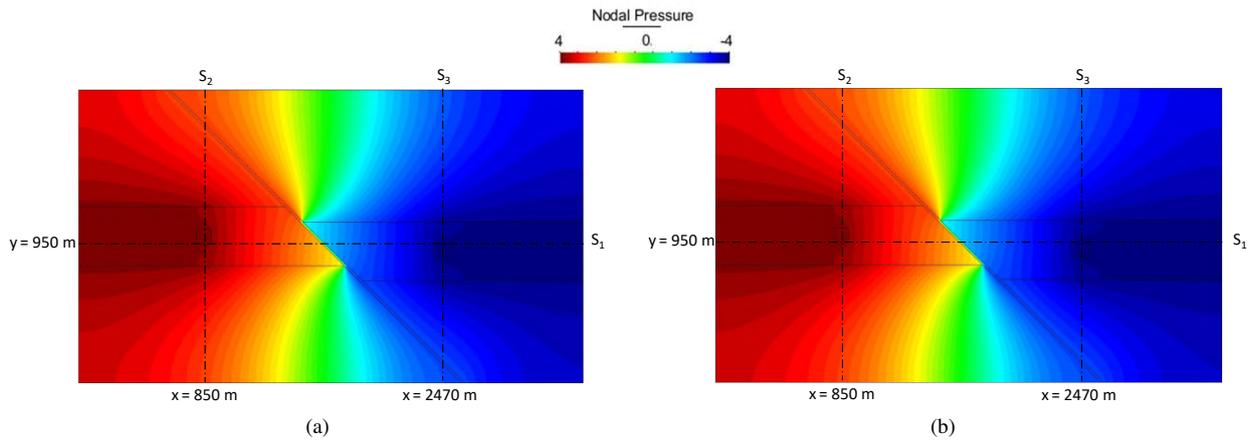


Figure 8: Second example. Pressure field of the (a) matching and (b) non-matching meshes.

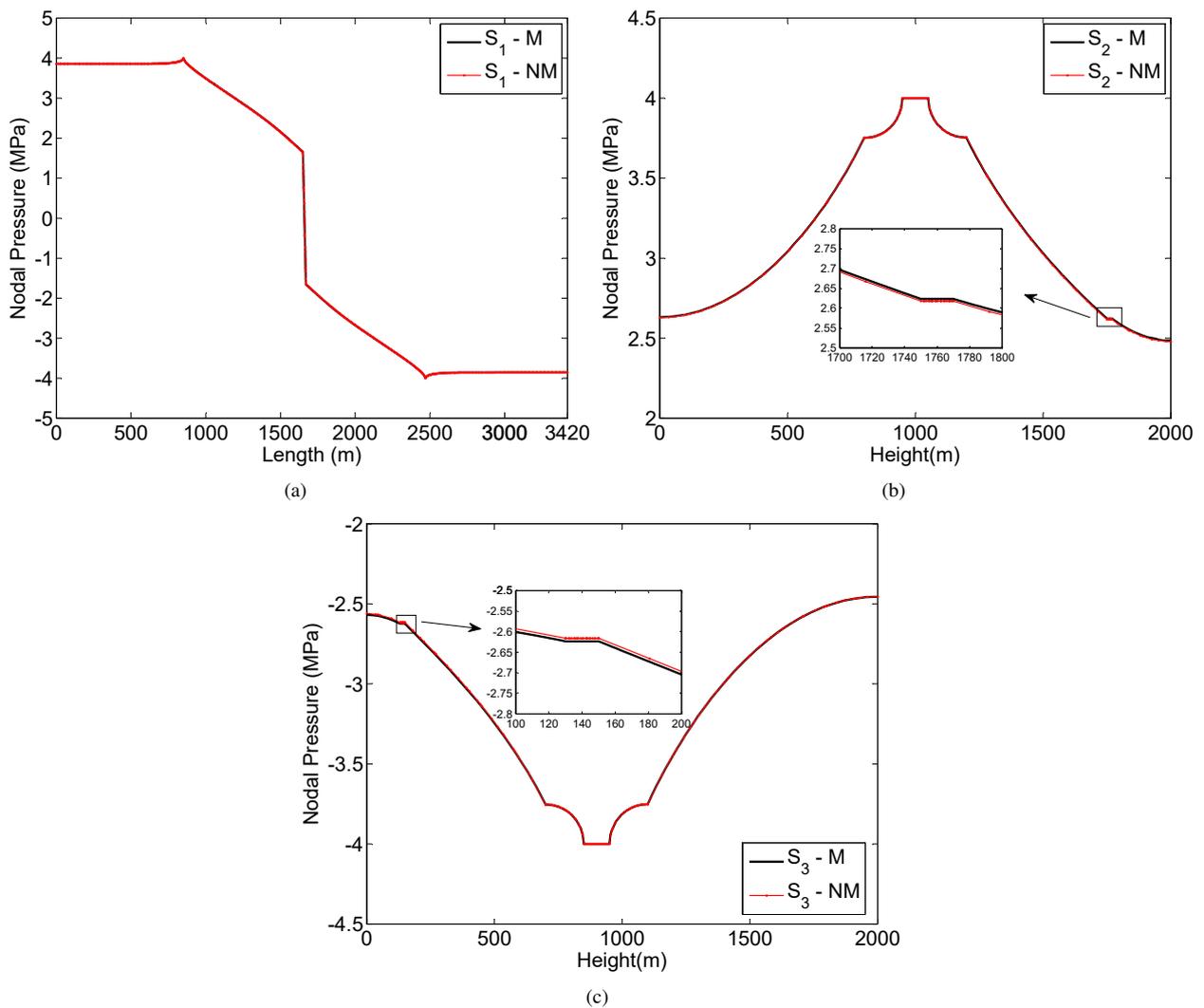


Figure 9: Convergence analysis of nodal pressures along section: (a) S_1 , (b) S_2 and (c) S_3 between the matching mesh (M) and non-matching mesh (NM).

5. CONCLUDING REMARKS

The coupling finite element technique proposed by Bitencourt Jr *et al.* (2015) for mechanical problems was properly adapted to couple non-matching meshes applied to simulate hydraulic problems, which showed able to model the behavior of fluid flow in saturated porous media represented by independent FE meshes. The bidimensional examples performed in this work demonstrated the ability of this new technique to couple non-matching meshes, ensuring the correct continuity of pressure field between domains with different mesh discretizations. Moreover, CFEs allows reducing the computational cost, once the degrees of freedom of the problem are reduced by using more optimized meshes.

6. ACKNOWLEDGEMENTS

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